SUPPLEMENTARY MATERIALS: Wasserstein Dictionary Learning: Optimal Transport-based unsupervised non-linear dictionary learning*

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SM1. Detailed derivations. Let us first introduce the notation:

$$\varphi \colon \frac{\mathbb{R}^N \times \mathbb{R}^N \to \mathbb{R}^N}{b_s, d \mapsto K^\top \frac{d}{K b_s}}.$$

SM1.1. Computation of $\partial_b \varphi$ **.** By definition:

(SM1)
$$\frac{\partial \varphi}{\partial b_s}(b_s, d) = -K^{\top} \Delta \left(\frac{d}{(Kb_s)^2}\right) K$$

In what follows, we will denote $\varphi_{NS}(b, D) = \left[\varphi(b_1, d_1)^\top, \dots, \varphi(b_S, d_S)^\top\right]^\top \in \mathbb{R}^{NS}$:

$$\partial_b \varphi_{NS}(b, D) = \begin{pmatrix} \frac{\partial \varphi(b_1, d_1)}{\partial b_1} & \mathbf{0}_{N \times N} & \dots & \mathbf{0}_{N \times N} \\ \mathbf{0}_{N \times N} & \frac{\partial \varphi(b_2, d_2)}{\partial b_2} & \dots & \mathbf{0}_{N \times N} \\ \vdots & & \ddots & \vdots \\ \mathbf{0}_{N \times N} & \dots & \mathbf{0}_{N \times N} & \frac{\partial \varphi(b_S, d_S)}{\partial b_S} \end{pmatrix}$$

SM1.2. Computation of Ψ_b . Taking the logarithm of (16) yields:

$$\log(\Psi(b, D, \lambda)) = \sum_{s} \lambda_s \log(\varphi(b_s, d_s))$$

The differentiation of which gives us:

$$\Delta\left(\frac{\mathbb{1}_{N}}{\Psi(b,D,\lambda)}\right)\partial_{b}\Psi(b,D,\lambda) = \begin{pmatrix}\lambda_{1}I_{N} & \dots & \lambda_{S}I_{N}\end{pmatrix}\Delta\left(\frac{\mathbb{1}_{NS}}{\varphi_{NS}(b,D)}\right)\partial_{b}\varphi_{NS}(b,D)$$

SM2)
$$\implies \Psi_{b} = [\partial_{b}\varphi_{NS}(b,D)]^{\top}\Delta\left(\frac{\mathbb{1}_{NS}}{\varphi_{NS}(b,D)}\right)J_{\lambda}\Delta(\Psi(b,D,\lambda))$$

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Where $J_{\lambda} = \begin{pmatrix} \lambda_1 I_N \\ \vdots \\ \lambda_S I_N \end{pmatrix} \in \mathbb{R}^{NS \times N}.$

SM1.3. Computation of Ψ_D . Let $i \in \{1, \ldots, S\}$.

$$\Psi(b, D, \lambda) = \prod_{s \neq i} \Delta(\varphi_c(b_s, d_s))^{\lambda_s} \cdot \left(K^\top \frac{d_i}{Kb_i}\right)^{\lambda_i}$$

And:

$$(SM3) \qquad \qquad \frac{\partial \left(K^{\top} \frac{d_i}{Kb_i}\right)^{\lambda_i}}{\partial d_i} = \lambda_i \Delta \left(K^{\top} \frac{d_i}{Kb_i}\right)^{\lambda_i - 1} K^{\top} \Delta \left(\frac{\mathbb{1}_N}{Kb_i}\right)$$
$$\implies \frac{\partial \Psi}{\partial d_i}(b, D, \lambda) = \lambda_i \frac{\Delta(\Psi(b, D, \lambda))}{\Delta \left(K^{\top} \frac{d_i}{Kb_i}\right)} K^{\top} \left(\frac{\mathbb{1}_N}{Kb_s}\right)$$

SM1.4. Computation of Φ_b .

$$\begin{aligned} \partial_{b}\Phi(b,D,\lambda) &= \begin{pmatrix} \Delta\left(\frac{1}{\varphi(b_{1},d_{1})}\right) \\ \vdots \\ \Delta\left(\frac{1}{\varphi(b_{3},d_{5})}\right) \end{pmatrix} \partial_{b}\Psi(b,d) \\ &- \begin{pmatrix} \Delta\left(\frac{\Psi(b,D,\lambda)}{\varphi(b_{1},d_{1})^{2}}\right) \frac{\partial\varphi(b_{1},d_{1})}{\partial b_{1}} & \mathbf{0}_{N\times N} & \dots & \mathbf{0}_{N\times N} \\ \mathbf{0}_{N\times N} & \Delta\left(\frac{\Psi(b,D,\lambda)}{\varphi(b_{2},d_{2})^{2}}\right) \frac{\partial\varphi(b_{2},d_{2})}{\partial b_{2}} & \dots & \mathbf{0}_{N\times N} \\ \vdots & \ddots & \vdots \\ \mathbf{0}_{N\times N} & \dots & \mathbf{0}_{N\times N} & \Delta\left(\frac{\Psi(b,D,\lambda)}{\varphi(b_{5},d_{5})^{2}}\right) \frac{\partial\varphi(b_{5},d_{5})}{\partial b_{5}} \end{pmatrix} \\ &= \Delta\left(\frac{1}{NS}_{NS}(b,D)\right) I_{N,S}^{T}(\partial_{b}\Psi(b,D,\lambda)) - \Delta\left(\frac{1}{NS}_{NS}(b,D)\right) \Delta(\Phi(b,D,\lambda))\partial_{b}\varphi_{NS}(b,D) \\ &= \Delta\left(\frac{1}{NS}_{NS}(b,D)\right) \left[I_{N,S}^{T}(\partial_{b}\Psi(b,D,\lambda)) - \Delta(\Phi(b,D,\lambda))\partial_{b}\varphi_{NS}(b,D)\right] \\ &\Longrightarrow \Phi_{b} = \left[\Psi_{b}I_{N,S} - [\partial_{b}\varphi_{NS}(b,D)]^{T} \Delta(\Phi(b,D,\lambda))\right] \Delta\left(\frac{1}{\varphi_{NS}(b,D)}\right) \\ &\stackrel{(SM2)}{=} \left[[\partial_{b}\varphi_{NS}(b,D)]^{T} \Delta\left(\frac{1}{NS}_{Q(b,D)}\right) J_{\lambda}\Delta(\Psi(b,D,\lambda))I_{N,S} \\ &- [\partial_{b}\varphi_{NS}(b,D)]^{T} \left[\Delta\left(\frac{1}{NS}_{Q(b,D)}\right) J_{\lambda}\Delta(\Psi(b,D,\lambda))I_{N,S} - \Delta(\Phi(b,D,\lambda))\right] \Delta\left(\frac{1}{\varphi_{NS}(b,D)}\right) \end{aligned}$$

$$(SM4) \\ &= \left[\partial_{b}\varphi_{NS}(b,D)\right]^{T} \left[\Delta\left(\frac{1}{NS}_{Q(b,D)}\right) J_{\lambda}\Delta(\Psi(b,D,\lambda))I_{N,S} - \Delta(\Phi(b,D,\lambda))\right] \Delta\left(\frac{1}{\varphi_{NS}(b,D)}\right) \end{aligned}$$

Where $I_{N,S} = [I_N, \ldots, I_N] \in \mathbb{R}^{N \times NS}$. Moreover, we have:

$$\begin{split} \Delta \left(\frac{\mathbbm{1}_{NS}}{\varphi(b,D)}\right) J_{\lambda} \Delta(\Psi(b,D,\lambda)) &= \begin{pmatrix} \Delta(1/\varphi(b_1,d_1)) & & \\ & \ddots & \\ & & \Delta(1/\varphi(b_S,d_S)) \end{pmatrix} \begin{pmatrix} \lambda_1 \Delta(\Psi(b,D,\lambda)) \\ \vdots \\ \lambda_S \Delta(\Psi(b,D,\lambda)) \end{pmatrix} \\ &= \begin{pmatrix} \lambda_1 \Delta \left(\frac{\Psi(b,D,\lambda)}{\varphi(b_1,d_1)}\right) & & \\ & \ddots & \\ & & \lambda_S \Delta \left(\frac{\Psi(b,D,\lambda)}{\varphi(b_S,d_S)}\right) \end{pmatrix} \\ &= \Delta(\Phi(b,D,\lambda)) \begin{pmatrix} \lambda_1 I_N \\ \vdots \\ \lambda_S I_N \end{pmatrix} \\ \Delta \left(\frac{\mathbbm{1}_{NS}}{\varphi(b,D)}\right) J_{\lambda} \Delta(\Psi(b,D,\lambda)) = \Delta(\Phi(b,D,\lambda)) J_{\lambda} \end{split}$$

Hence, in (SM4):

$$\Phi_b = [\partial_b \varphi_{NS}(b, D)]^\top \Delta(\Phi(b, D, \lambda)) [J_\lambda I_{N,S} - I_{NS}] \Delta\left(\frac{\mathbb{1}_N}{\varphi_{NS}(b, D)}\right)$$

SM1.5. Computation of Φ_D . Let $i \in \{1, ...\}$. $\forall s \neq i$, the only dependency in d_i of $\Phi^s(b, D, \lambda)$ resides in Ψ (see (17)), hence:

$$\begin{aligned} \forall s \neq i, \frac{\partial \Phi^s}{\partial d_i} &= \Delta \left(\frac{\mathbbm{1}_N}{\varphi(b_s, d_s)} \right) \partial_{d_i} \Psi \\ & \stackrel{(\text{SM3})}{=} \lambda_i \frac{\Delta(\Psi(B, D, \lambda))}{\Delta(\varphi(b_s, d_s)) \Delta(\varphi(b_i, d_i))} K^\top \Delta \left(\frac{\mathbbm{1}_N}{Kb_i} \right) \\ & \stackrel{(17)}{=} \lambda_i \frac{\Delta(\Phi^i(B, D, \lambda))}{\Delta(\varphi(b_s, d_s))} K^\top \Delta \left(\frac{\mathbbm{1}_N}{Kb_i} \right) \end{aligned}$$

As for s = i, we have:

$$\begin{split} \Phi^{i}(b,D,\lambda) &= \frac{\Psi(b,D,\lambda)}{K^{\top}\frac{d_{i}}{Kb_{i}}} \\ \Longrightarrow \ \frac{\partial \Phi^{i}}{\partial d_{i}}(b,D,\lambda) &= \Delta\left(\frac{\mathbbm{1}_{N}}{\varphi(b_{1},d_{1})}\right) \partial_{D}\Psi(b,D,\lambda) - \frac{\Delta(\Psi(b,D,\lambda))}{\Delta(\varphi_{i}(b_{i},d_{i})^{2})} \partial_{d_{i}}\varphi(b_{i},d_{i}) \\ &= \Delta\left(\frac{\mathbbm{1}_{N}}{\varphi(b_{1},d_{1})}\right) \partial_{D}\Psi(b,D,\lambda) - \frac{\Delta(\Phi^{i}(b,D,\lambda))}{\Delta(\varphi(b_{i},d_{i}))} K^{\top}\left(\frac{\mathbbm{1}_{N}}{Kb_{i}}\right) \\ &= (\lambda_{i}-1)\frac{\Delta(\Phi^{i}(b,D,\lambda))}{\Delta(\varphi(b_{i},d_{i}))} K^{\top}\Delta\left(\frac{\mathbbm{1}_{N}}{Kb_{i}}\right) \end{split}$$

Algorithm SM1 HeavyballSinkhorn: Computation of approximate Wasserstein barycenters with acceleration

Inputs: Data $x \in \Sigma_N$, atoms $d_1, \ldots, d_S \in \Sigma_N$, weights $\lambda \in \Sigma_S$, extrapolation parameter $\tau \leq 0$ $\forall s, b_s^{(0)} := \mathbf{1}_N$ for l = 1 to L step 1 do $\forall s, \tilde{a}_s^{(l)} := \frac{d_s}{K b_s^{(l-1)}}$ $\forall s, a_s^{(l)} := \left(a_s^{(l-1)}\right)^{\tau} \left(\tilde{a}_s^{(l)}\right)^{1-\tau}$ $p := \prod_s \left(K^{\top} a_s^{(l)}\right)^{\lambda_s}$ $\forall s, \tilde{b}_s^{(l)} := \frac{p}{K^{\top} a_s^{(l)}}$ $\forall s, b_s^{(l)} := \left(b_s^{(l-1)}\right)^{\tau} \left(\tilde{b}_s^{(l)}\right)^{1-\tau}$ od **Outputs:** $P^{(L)}(D, \lambda) := p$

Algorithm SM2 GeneralizedSinkhorn: Computation of unbalanced barycenters with acceleration

Inputs: Data $x \in \Sigma_N$, atoms $d_1, \ldots, d_S \in \Sigma_N$, weights $\lambda \in \Sigma_S$, extrapolation parameter $\tau \leq 0$, KL parameter $\rho > 0$ $\forall s, b_s^{(0)} := \mathbf{1}_N$ for l = 1 to L step 1 do $\forall s, \tilde{a}_s^{(l)} := \left(\frac{d_s}{Kb_s^{(l-1)}}\right)^{\frac{\rho}{\rho+\gamma}}$ $\forall s, a_s^{(l)} := \left(a_s^{(l-1)}\right)^{\tau} \left(\tilde{a}_s^{(l)}\right)^{1-\tau}$ $p := \left(\sum_{s=1}^S \lambda_s \left(K^{\top} a_s^{(l)}\right)^{\frac{\rho}{\rho+\gamma}}\right)^{\frac{\rho+\gamma}{\gamma}}$ $\forall s, \tilde{b}_s^{(l)} := \left(\frac{p}{K^{\top} a_s^{(l)}}\right)^{\frac{\rho}{\rho+\gamma}}$ $\forall s, b_s^{(l)} := \left(b_s^{(l-1)}\right)^{\tau} \left(\tilde{b}_s^{(l)}\right)^{1-\tau}$ od

Outputs: $P^{(L)}(D, \lambda) := p$

SM2. Generalized barycenters.

SM3. Additional results.



Figure SM1: Span of our 2-atoms dictionary for weights $(1 - t, t), t \in \{0, \frac{1}{4}, \frac{1}{2}, \frac{3}{4}, 1\}$ when trained on images of digits 1, 2, 3, 4. See the first columns of Figure C.1 for comparison with first WPGs.



Figure SM2: Same as Figure 6 when training on images of the digit 1.



Figure SM3: Same as Figure 6 when training on images of the digit 3.



Figure SM4: Same as Figure 6 when training on images of the digit 4.

SM3.1. MNIST and Wasserstein Geodesics.



Figure SM5: Extreme wavelength PSFs in the dataset and atoms learned from NMF. See Figure 9 for those learned using our method.

SM3.2. Point Spread functions.

SM3.3. Wasserstein faces.

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Figure SM6: Similarly to Figure 13, we compare our method to the Eigenfaces [SM2] approach, NMF and K-SVD as a tool to represent faces on a low dimensional space.



Figure SM7: Similarly to Figure 14, we compare the atoms obtained using different loss functions, ranking them by mean PSNR: (a) $\overline{PSNR} = 33.81$, (b) $\overline{PSNR} = 33.72$, (c) $\overline{PSNR} = 32.95$ and (d) $\overline{PSNR} = 32.34$