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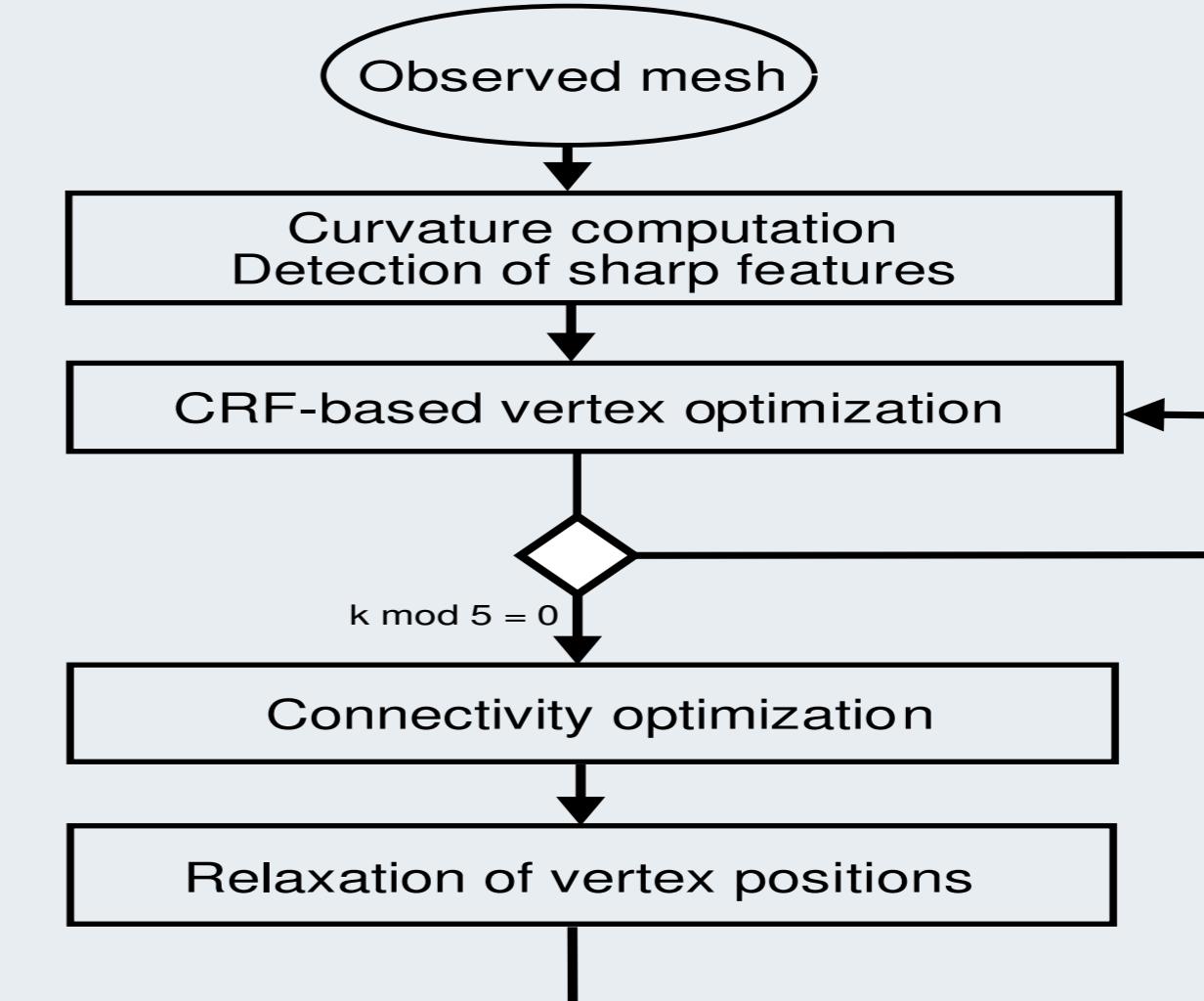
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## Goals : remeshing with

- Better triangle quality
- Better vertex valence
- Preserved sharp features
- High fidelity to the initial surface

## Remeshing pipeline



## CRF-based vertex optimization : Gibbs energy minimization/probability maximization formulation

- Energy functional to minimize

$$U(x, y) = \sum_{r,s,t \in \mathcal{C}_3} \lambda_{shape} \psi_{shape}(x_r, x_s, x_t) + \sum_{s \in G} \lambda_{data} \psi_{data}(x_s, y) \quad (1)$$

$$\psi_{shape}(x_r, x_s, x_t) = \frac{\text{circumradius}(x_r, x_s, x_t)}{\min(\|x_r - x_s\|, \|x_r - x_t\|, \|x_s - x_t\|)}$$

$$\psi_{data} = \frac{d}{d + |\varrho_{min}|} \tilde{x}_{s1}^2 + \frac{d}{d + |\varrho_{max}|} \tilde{x}_{s2}^2 + \tilde{x}_{s3}^2$$

(squared distance to the surface expressed in the closest observation Frenet frame)

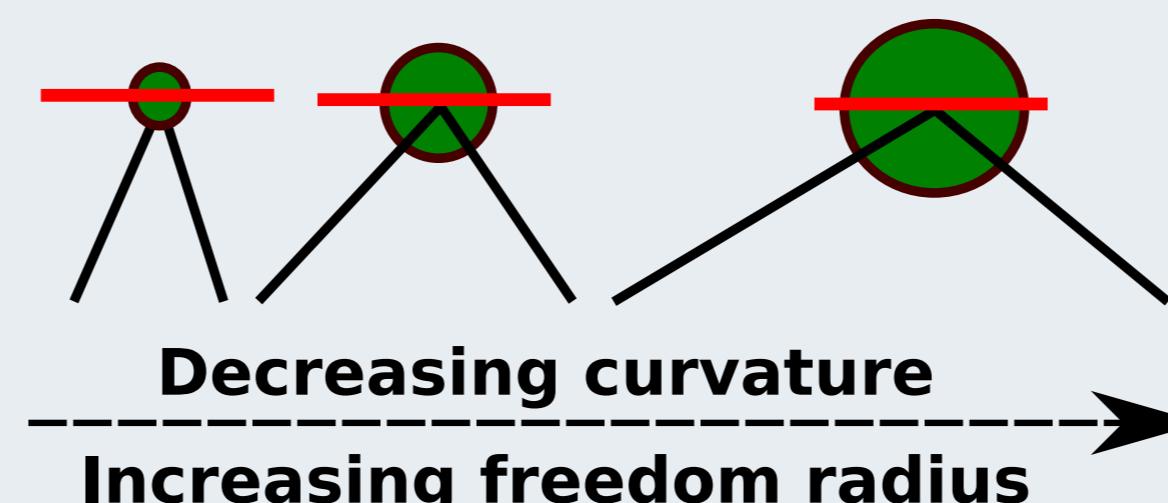
$$\text{Minimize } U(x)/\text{maximize } P(x) = e^{-U(x)}$$

■ Complex continuous optimization problem

■ Bayesian MAP estimation (inference)

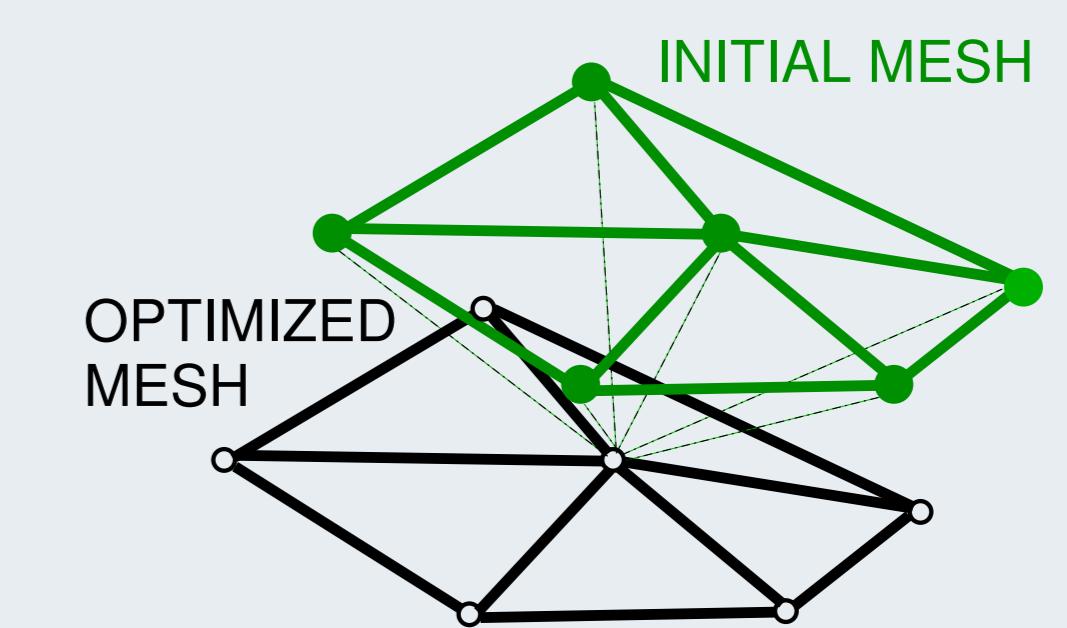
- Candidate proposals

- On the tangent plane
- In a freedom sphere adapted to local curvature
- Angle-based and Laplacian smoothing + guided random



- Global decision for each vertex (keep the new or the current position ?)

- Global combination of local candidates
- Kolmogorov et al.'s graph cut technique : st-graph representing the energy function+min cut/max flow to find out the configuration with minimal energy



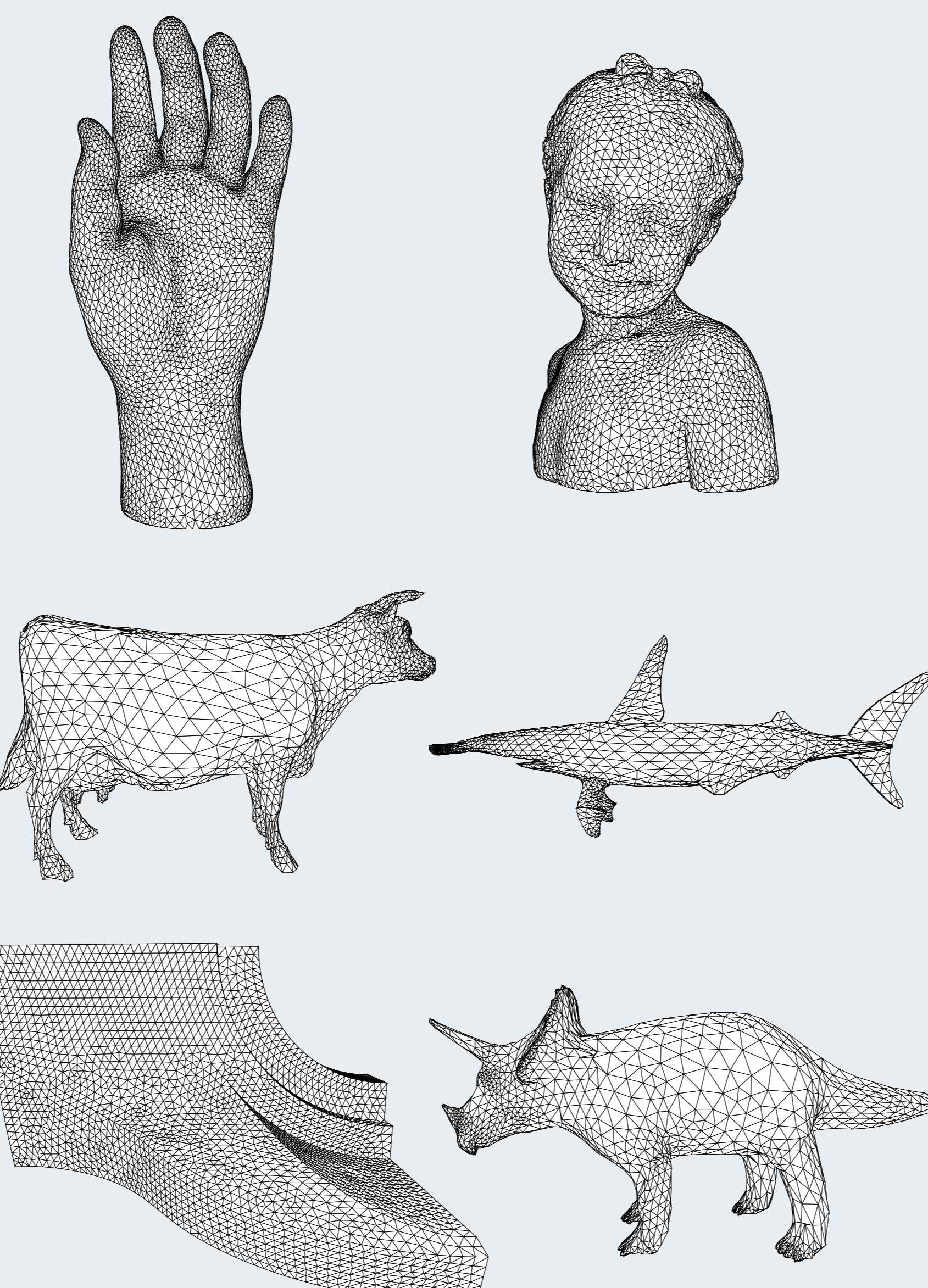
The initial mesh (input mesh) is used as the reference geometry for optimization purposes. The optimized/hidden mesh represents the dependency graph of the CRF. Each site node (optimized vertex) is possibly attached to all observed data.

## Mesh connectivity optimization + vertex relaxation

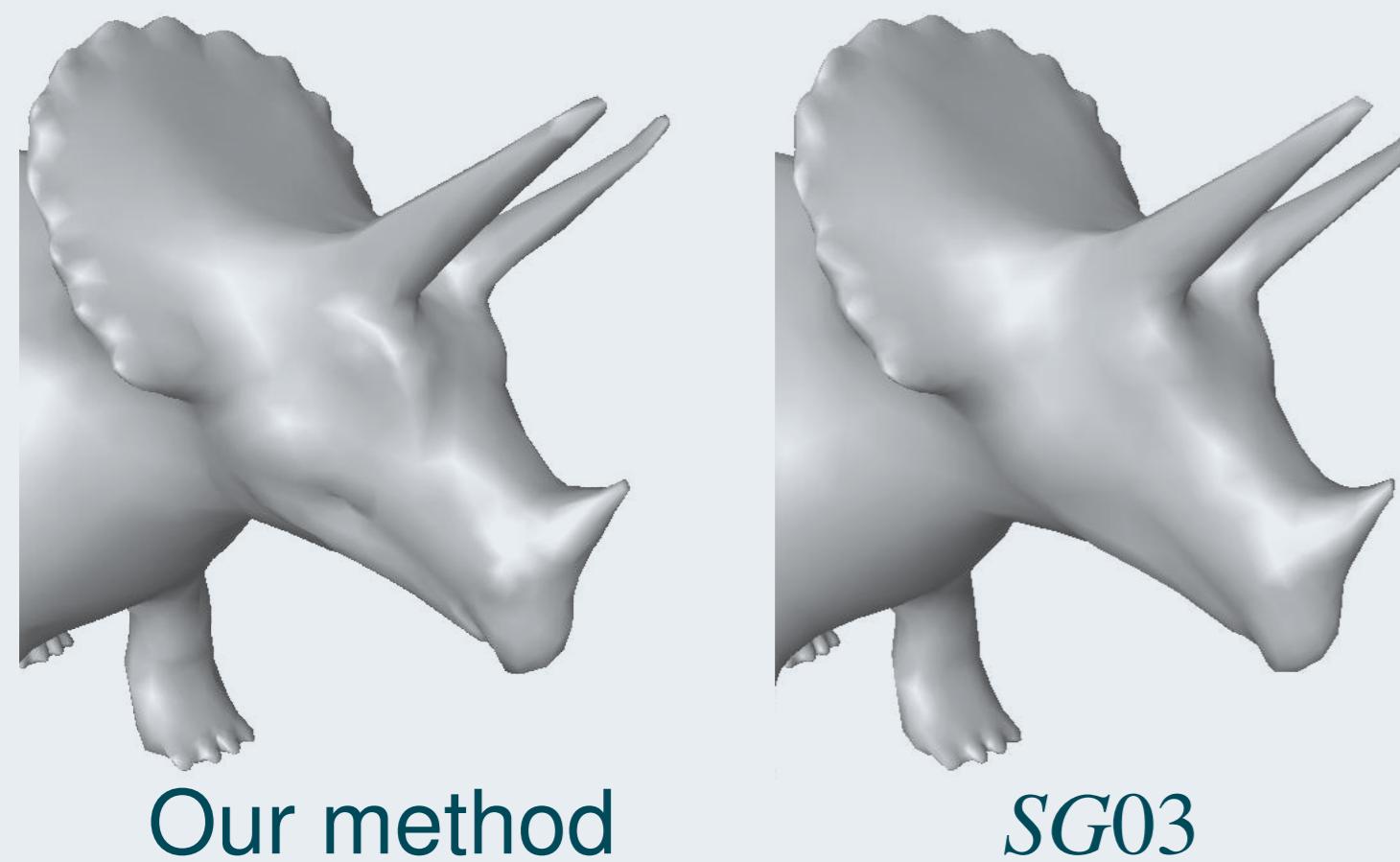
- Topological local operators
- Edge-flip/split/collapse
- Vertex split
- Do them smoothly : priority queue on the shape improvement

- Vertex relaxation
- Angle-based smoothing
- Laplacian smoothing
- Project them on the tangent plane
- Let feature vertices unchanged

## Remeshed models



## Comparison with SG03



## Conclusions

- We have presented a CRF-based vertex repositioning for solving a complex continuous optimization problem using discrete optimization techniques.
- The presented results show a good triangle shape quality while maintaining a high surface fidelity.

## Statistics on the remeshed models

Model	#v	Irreg (%)	Amin (deg)	Amaz (deg)	Er <sub>Haus</sub> (10 <sup>-3</sup> )	Er <sub>RMS</sub> (10 <sup>-3</sup> )
Fandisk (init)	6495	20	43.4	86.1	-	-
Fandisk (Liu)	6495	20	44.7	82.0	3.3	0.8
Fandisk (our)	6361	<b>14</b>	<b>48.2</b>	<b>77.4</b>	<b>1.3</b>	<b>0.03</b>
Cow (init)	2892	53	30.8	92.4	-	-
Cow (Liu)	2892	53	35.1	88.2	5.3	0.9
Cow (our)	2743	<b>36</b>	<b>40.7</b>	<b>83.8</b>	<b>5.0</b>	<b>0.7</b>
Shark (init)	2560	31	20.8	97.4	-	-
Shark (Liu)	2560	31	26.2	107.5	<b>3.0</b>	<b>0.3</b>
Shark (Sur1)	2560	30	<b>50.6</b>	<b>71.1</b>	6.8	0.8
Shark (our)	2345	<b>23</b>	32.4	96.3	3.8	<b>0.3</b>
Hand (init)	7950	58	32.3	94.1	-	-
Hand (Liu)	7950	58	34.3	92.2	8.8	0.4
Hand (Val)	6802	45	46.1	77.5	2.6	<b>0.2</b>
Hand (our)	6800	<b>28</b>	<b>48.1</b>	<b>76.5</b>	<b>2.0</b>	<b>0.2</b>
Bimba (init)	8857	62	34.2	92.7	-	-
Bimba (Liu)	8857	62	38.1	87.0	4.9	0.5
Bimba (Sur1)	8857	<b>20</b>	<b>53.6</b>	<b>67.6</b>	6.0	0.5
Bimba (Val)	8143	48	45.2	78.1	6.0	0.4
Bimba (our)	8143	37	46.9	77.0	<b>3.4</b>	<b>0.2</b>
Triceratops (init)	2832	59	29.6	95.5	-	-
Triceratops (Sur2)	2758	<b>13</b>	<b>42.2</b>	<b>82.5</b>	8.4	1.1
Triceratops (our)	2693	37	41.0	83.9	<b>3.9</b>	<b>0.5</b>

Liu, Val, Sur1 and Sur2 correspond respectively to LTJW07, VCP08, SAG03 and SG03.