# Application of Fusion-Fission to the multi-way graph partitioning problem 

Charles-Edmond Bichot<br>Laboratoire d'Optimisation Globale, École Nationale de l'Aviation Civile/Direction des Services de la Navigation Aérienne, 7 av. Edouard Belin, 31055 Toulouse, France, bichot@recherche.enac.fr, WWW home page: http://www.recherche.enac.fr/~ ${ }^{\text {bichot }}$


#### Abstract

This paper presents an application of the Fusion-Fission method to the multi-way graph partitioning problem. The Fusion-Fission method was first designed to solve the normalized cut partitioning problem. Its application to the multi-way graph partitioning problem is very recent, thus the Fusion-Fission algorithm has not yet been optimized. Then, the Fusion-Fission algorithm is slower than the state-of-the-art graph partitioning packages. The Fusion-Fission algorithm is compared with JOSTLE, METIS, CHACO and PARTY for four partition's cardinal numbers: $2,4,8$ and 16 , and three partition balance tolerances: 1.00 , 1.01 and 1.03. Results show that up to two thirds of time are the partitions returned by Fusion-Fission of greater quality than those returned by state-of-the-art graph partitioning packages.


## 1 Introduction

For ten years, the state-of-the-art method to solve the multi-way graph partitioning problem is the multilevel method. The multilevel method often used a graph growing algorithm for the partitioning task and a Kernighan-Lin type refinement algorithm. This method has been introduced in [HL95b,KK95,AHK97]. It is a very efficient process which is very fast too. It consists in reducing the number of vertices of the graph, which is sometimes very high (more than 100,000 vertices), by coarsening them. Then, a partition of the coarsenest graph (less than 100 vertices) is built, generally with a graph growing algorithm [KK98a]. After that, the vertices of the partition are successively un-coarsened and the partition refined with a Kernighan-Lin algorithm [KL70,FM82] or a helpful set algorithm [DMP95].

Graph partitioning has many applications. The most famous of them are parallel computing, VLSI design and engineering computation. Thus, graph partitioning is an important combinatorial optimization problem. Because of its great number of applications, there are different graph partitioning problems. The aim of this paper is to study the most classical of them, the multi-way graph partitioning problem, also called $k$-way graph-partitioning problem [KK98c]. The other graph partitioning problems, such as the Normalized-Cut partitioning problem
[SM00,DGK04] or the Ratio-Cut partitioning problems [DGK07], are not presented in this paper.

This paper presents an application of the Fusion-Fission method to the multiway graph partitioning problem. The Fusion-Fission method was first created to solve the Normalized-Cut graph partitioning problem [Bic06,Bic07]. Because the multi-way graph partitioning problem and the normalized-cut graph partitioning problems are strongly related, it is interesting to evaluate the efficiency of the same method to both problems, as it has been done for the multilevel method [DGK07].

The work presented in this paper is the first adaptation of Fusion-Fission to the multi-way graph partitioning problem. Thus, all components of FusionFission presented in [Bic07] do no appear in this preliminary adaptation. However, partitions found by this adaptation are quite good regarding partitions returned by state-of-the-art graph partitioning packages.

## 2 Graph partitioning

The multi-way graph partitioning problem consists in finding a partition of the vertices of a graph into parts of the same size, while minimizing the number of edges between parts. It is well-known that the multi-way graph partitioning problem is NP-complete.

The difficulty of the task is to keep the sizes of the parts equal while minimizing the edge-cut. The value which represents the difference between the sizes of the parts is named the balance of the partition. Because a small difference between the sizes of the parts may lead to a lower edge-cut [ST97], lots of results are presented with partitions not perfectly balanced.

Definition 1 (Partition of the vertices of a graph). Let $G=(V, E)$ be an undirected graph, with $V$ its set of vertices and $E$ its set of edges. A partition of the graph into $k$ parts is a set $P_{k}=\left\{V_{1}, \ldots, V_{k}\right\}$ of sub-sets of $V$ such that:

- No element of $P_{k}$ is empty.
- The union of the elements of $P_{k}$ is equal to $V$.
- The intersection of any two elements of $P_{k}$ is empty.

The number of parts $k$ of the partition $P_{k}$ is named the cardinal number of the partition.

Assume that the graph $G$ is weighted. For each vertex $v_{i} \in V$, let $w\left(v_{i}\right)$ be its weight. For each edge $\left(v_{i}, v_{j}\right) \in E$, let $w\left(v_{i}, v_{j}\right)$ be its weight. Then, the weight of a set of vertices $V^{\prime} \subseteq V$ is the sum of the weight of the vertices of $V^{\prime}$ : $w\left(V^{\prime}\right)=\sum_{v \in V^{\prime}} w(v)$.

Definition 2 (Balance of a partition). Let $P_{k}=\left\{V_{1}, \ldots, V_{k}\right\}$ be a partition of a graph $G=(V, E)$ into $k$ parts. The average weight of a part is: $W_{\text {average }}=$
$\frac{w(V)}{k}$. The balance of a partition is defined as the maximum weight of all parts divided by the average weight of a part:

$$
\operatorname{balance}\left(P_{k}\right)=\frac{\max _{V_{i} \in P_{k}} w\left(V_{i}\right)}{W_{\text {average }}}=\frac{k}{w(V)} \max _{V_{i} \in P_{k}} w\left(V_{i}\right) .
$$

The objective function to minimize is the cut function. It is defined as the sum of the weight of the edges between the parts. More formally, let $V_{1}$ and $V_{2}$ be two elements of $P_{k}$ :

$$
\operatorname{cut}\left(V_{1}, V_{2}\right)=\sum_{u \in V_{1}, v \in V_{2}} w(u, v)
$$

Then, the cut objective function is defined as:

$$
\operatorname{cut}\left(P_{k}\right)=\sum_{V_{i}, V_{j} \in P_{k}, i<j} \operatorname{cut}\left(V_{i}, V_{j}\right) .
$$

The partition which has the lowest cut value is the solution of the multiway graph partitioning problem. However, because of the size of the graph to partition (several thousands of vertices), and because of the combinatorial nature of the problem, the partition with the lowest cut value can not be found. Thus, combinatorial optimization methods are used to solve this problem.

## 3 The Fusion-Fission adaptation to multi-way graph partitioning

Because principles of Fusion-Fission are described in [Bic07], this paper presents only succinctly this method. Fusion-Fission principles are based on nuclear force between nucleons. This force is responsible for binding of protons and neutrons into atomic nuclei. In the nature, the fifty-six particles of an iron nucleus are more tightly bound together than in any other element. Thus, the Fusion-Fission optimization process consists in splitting and merging atoms to create atoms of maximum binding energy. Nucleons of big atoms are merged into atoms with few nucleons.

An analogy with graph partitioning is easy. Let the nucleons be the vertices of the graph and the atoms the parts of the partition. The binding energy between two nucleons is the edge weight between the corresponding vertices. According to the Fusion-Fission process, parts of the partition are successively merged and split. Then, the cardinal number of the partition changes during the process. Resulting atoms of the Fusion-Fission process should be atoms of the same size. Which means that the final partition is perfectly balanced.

To be as close as possible to the process described before, the Fusion-Fission application to multi-way graph partitioning is an iteration process which works as follows: at each step of the process, a new partition $P_{l^{\prime}}^{t+1}$ is created based on the preceding partition $P_{l}^{t}$. The fission process consists in splitting each part of
the partition $P_{l^{\prime}}^{t+1}$ into $l$ parts. Because of its efficiency, the multilevel method has been chosen for the splitting. The fusion process consists in merging the $l^{\prime} * l$ parts into a partition $P^{\prime}$ of $l^{\prime}$ parts. The merging can be viewed as graph partitioning problem where the vertices of the graph are the $l^{\prime} * l$ parts. Thus, a multilevel method has been chosen for the merging too. Then, the partition $P^{\prime}$ is refined using a Kernighan-Lin type algorithm $(K L)$. The resulting partition is the partition $P_{l^{\prime}}^{t+1}$. The initial partition, $P_{k}^{0}$, is provided by the multilevel method.

The algorithm 1 presents the Fusion-Fission application to multi-way graph partitioning. The number of part of the new partition, $l^{\prime}$, changes at each iteration. We decided to force it to follow a binomial distribution centered in $k$. Then, a list of numbers which follow this binomial distribution is constructed at the beginning of the Fusion-Fission algorithm. Then, each iteration starts by selecting a new number of part $l^{\prime}$ in this list.

The multilevel method and the Kernighan-Lin type algorithm ( $K L$ in the algorithm 1) used are those of the pMETIS software and are both described in [KK98a]. The pMETIS software does not refer to the parallel implementation of METIS, but pMETIS is the name given of the recursive bisection software implemented in the serial METIS package.

The particularity of the Fusion-Fission algorithm is to find several partitions of different cardinal numbers. Moreover, for each partition found during the algorithm's iteration, refinement is a four-step process. The partition is first refined for a balance of 1.00 , then for a balance of 1.01 , and after, for balances of 1.03 and 1.05. This four-step refinement process greatly decrease the computation time of the algorithm. Since the algorithm code is not optimized as much as the multilevel softwares, its computation time is less relevant than partition quality.

## 4 Comparison with state-of-the-art graph partitioning packages

### 4.1 Benchmarks graphs

The performance of the Fusion-Fission adaptation to multi-way graph partitioning is evaluated on a wide range of tests graphs arising in different application domains. These tests graphs have been chosen among classical benchmarks in the literature of graph partitioning. Some of these benchmarks have been tested in some recent papers [BGOM03,SWC04,KcR04,DGK07]. These graphs are both vertex and edge unweighted. The characteristics of these graphs are described in table 1.

All of these benchmarks graphs can be downloaded at the University of Greenwich graph partitioning archive (May 2007): http://staffweb.cms.gre.ac.uk/~c.walshaw/partition/

All the experiments in this paper were performed on an Intel Pentium IV 3.0 GHz processor with 1 Go of memory, running a GNU/Linux Debian operating system.

```
Algorithm 1 Fusion-Fission
    procedure FusionFission \((G=(V, E), k, n, p M E T I S, K L)\)
        \(l \leftarrow k\)
        \(P \leftarrow p \operatorname{METIS}(G, k)\)
        \(P_{k}^{0} \leftarrow P=\left\{P_{1}, \ldots, P_{k}\right\}\)
        for \(t=1\) to \(n\) do
            choose a new number of parts \(l^{\prime}\)
            \(P_{l}^{t}=\left\{P_{1}, \ldots, P_{l}\right\}\)
            for \(j=1\) to \(l\) do
                    \(V_{l^{\prime}}^{\prime} \leftarrow p \operatorname{METIS}\left(P_{j}, l^{\prime}\right)\)
                    \(V^{\prime} \leftarrow V^{\prime} \cup V_{l^{\prime}}^{\prime}\)
            end for
            make a graph \(G^{\prime}\) based on the set of parts \(V^{\prime}\)
            \(P_{l^{\prime}}^{t+1} \leftarrow p \operatorname{METIS}\left(G^{\prime}, l^{\prime}\right)\)
            \(P^{\prime} \leftarrow K L(P)\)
            if \(l^{\prime}=k\) and \(\operatorname{cut}\left(P^{\prime}\right)<\operatorname{cut}(P)\) then
                    \(P \leftarrow P^{\prime}\)
            end if
        end for
        return \(P\)
    end procedure
```

Table 1. Benchmark graphs characteristics.

| Graph name | Size |  | Degree |  | Description (source) |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\|V\|$ | $\|E\|$ | min | max avg |  |
| add20 | 2395 | 7462 | 1 | $123 \quad 6.23$ | 20-bit adder (Motorola) |
| data | 2851 | 15093 | 3 | 1710.59 |  |
| 3elt | 4720 | 13722 | 3 | $9 \quad 5.81$ | 2D nodal graph (NASA/RIACS) |
| uk | 4824 | 6837 | 1 | $3 \quad 2.83$ | 2D dual graph |
| add32 | 4960 | 9462 | 1 | 313.82 | 32-bit adder (Motorola) |
| bcsstk33 | 8738 | 291583 | 19 | 14066.74 | 3D stiffness matrix (Boeing) |
| whitaker3 | 9800 | 28989 | 3 | $8 \quad 5.92$ | 2D nodal graph (NASA/RIACS) |
| crack | 10240 | 30380 | 3 | $9 \quad 5.93$ | 2D nodal graph |
| wing_nodal | 10937 | 75488 | 5 | 2813.80 | 3D nodal graph |
| fe_4elt2 | 11143 | 32818 | 3 | $12 \quad 5.89$ |  |
| vibrobox | 12328 | 165250 | 8 | 12026.81 | Sparse matrix |
| bcsstk29 | 13992 | 302748 | 4 | 7043.27 | 3D stiffness matrix (Boeing) |
| 4 elt | 15606 | 45878 | 3 | $10 \quad 5.88$ | 2D nodal graph (NASA/RIACS) |
| fe_sphere | 16386 | 49152 | 4 | $6 \quad 6.00$ |  |
| cti | 16840 | 48232 | 3 | $6 \quad 5.73$ | 3D semi-structured matrix |
| memplus | 17758 | 54196 | 1 | $573 \quad 6.10$ | Memory circuit (Motorola) |
| cs4 | 22499 | 43858 | 2 | 43.90 | 3D dual graph |
| bcsstk30 | 28924 | 1007284 | 3 | 21869.65 | 3D stiffness matrix (Boeing) |
| bcsstk31 | 35588 | 572914 | 1 | 18832.20 | 3D stiffness matrix (Boeing) |
| bcsstk32 | 44609 | 985046 | 1 | 21544.16 | 3D stiffness matrix (Boeing) |
| t60k | 60005 | 89440 | 2 | $3 \quad 2.98$ | 2D dual graph |
| wing | 62032 | 121544 | 2 | 43.92 | 3D dual graph |
| brack2 | 62631 | 366559 | 3 | 3211.71 | 3D nodal graph (NASA/RIACS) |

### 4.2 Some graph partitioning packages

The quality of the partitions produced by the Fusion-Fission algorithm is compared with those generated on the same computer by several public domain graph partitioning softwares:

- The CHACO software [HL95a]. This software includes multilevel and spectral algorithms. Because it is more efficient than the spectral algorithm, only the multilevel algorithm of CHACO, described in [HL95b], is compared with Fusion-Fission.
- The JOSTLE software [Wal02]. It is based on a multilevel multi-way partitioning algorithm [WC00].
- The METIS package [KK98b]. This package provides both the pMETIS and the kMETIS softwares. kMETIS is a direct multi-way partitioning algorithm [KK98c]. pMETIS uses a recursive bisection algorithm [KK98a].
- The PARTY software [PD98]. This software is is based on a multilevel algorithm and a helpful-sets refinement algorithm [DMP95].

From all of this softwares, two have a balance parameter : JOSTLE and CHACO (with KL_IMBALANCE). The two others found partitions with a variable balance.

### 4.3 Comparisons between graph partitioning softwares

To be compared with the other algorithms, the Fusion-Fission algorithm has been limited to 2,000 iterations. Then, its runtime is between one minute and one hour. This computation time is quite long regarding those of graph partitioning packages which is often less than a second. There are some explanations to this deficiency. The Fusion-Fission algorithm has not been optimized. It makes four refinement steps instead of one (see section 3). However, the Fusion-Fission algorithm is not slow in comparison with metaheuristics applied to graph partitioning [BGOM03,SWC04] which have a computation time of several hours to several days.

Tables 2 and 3 present some comparisons between the public graph partitioning packages presented in section 4.2 and the Fusion-Fission algorithm. Four cardinals numbers have been chosen: $k=2,4,8$ and 16 . CHACO naturally finds partition perfectly balanced. Its results are compared with those of JOSTLE and Fusion-Fission for balance $=1.00$. pMETIS (labeled pM. in tables 2 and 3) finds partitions for a balance number of 1.01, thus it is compared with JOSTLE and Fusion-Fission for this imbalance. kMETIS and PARTY are compared with JOSTLE and Fusion-Fission for balance $=1.03$. When an algorithm do not find a partition for the given balance, the result is marked not available (N/A in tables 2 and 3 ).

In Tables 2 and 3, lines heading "Best" summarize the number of times the algorithms found the best partition quality over the 23 graphs of this benchmark, regarding results of the other algorithms for the same balance. Results show that Fusion-Fission outperforms the other algorithms in all cases except for $k=8$ and
$k=16$ with a balance of 1.00 . In the two last cases, the Fusion-Fission algorithm does as well as the JOSTLE software. The Fusion-Fission algorithm has not been constrained to find perfectly balanced partitions even if it tries to do so. Thus, in a few cases it does not find perfectly balanced partitions. The Fusion-Fission algorithm is particularly good for the two smallest cardinals numbers, $k=2$ and $k=4$. It can be noticed that the JOSTLE software does almost as well as the other softwares, except when it is compared with pMETIS for $k=16$ and balance $=1.03$.

## 5 Conclusion

A new multi-way graph partitioning method has been presented in this paper. This method named Fusion-Fission is based on a previous work we made to solve the normalized cut graph partitioning problem [Bic06,Bic07]. The adaptation of Fusion-Fission to the multi-way graph partitioning problem uses the pMETIS multilevel algorithm and its Kernighan-Lin refinement algorithm.

This method has been compared with four state-of-the-art graph partitioning packages: JOSTLE, METIS, CHACO and PARTY. Classical benchmarks have been used. The partitions searched are of cardinal numbers $2,4,8$ and 16 , with a balance of $1.00,1.01$ and 1.03 . Results show that up to two thirds of time are the partitions returned by Fusion-Fission of greater quality than those returned with state-of-the-art graph partitioning packages.

Since Fusion-Fission takes much longer time than state-of-the-art graph partitioning packages, it may bee difficult to used it for parallel matrix applications. However, it can be advantageously be used for fields where run-time is less of a concern, as VLSI layout or air traffic management problems.

## References

[AHK97] Charles J. Alpert, Jen-Hsin Huang, and Andrew B. Kahng. Multilevel circuit partitioning. In Proceedings of the ACM/IEEE Design Automation Conference, pages 530-533, 1997.
[BGOM03] R. Baños, C. Gil, J. Ortega, and F.G. Montoya. Multilevel heuristic algorithm for graph partitioning. In Proceedings of the European Workshop on Evolutionary Computation in Combinatorial Optimization, pages 143-153, 2003.
[Bic06] Charles-Edmond Bichot. A metaheuristic based on fusion and fission for partitioning problems. In Proceedings of the 20th IEEE International Parallel and Distributed Processing Symposium, 2006.
[Bic07] Charles-Edmond Bichot. A new method, the fusion fission, for the relaxed k -way graph partitioning problem, and comparisons with some multilevel algorithms. Journal of Mathematical Modeling and Algorithms (JMMA), 6(3):319-344, 2007.
[DGK04] Inderjit S. Dhillon, Yuqiang Guan, and Brian Kullis. Kernel k-means, spectral clustering, and normalized cuts. In Proceedings of the 10th ACM International Conference on Knowledge Discovery and Data Mining (KDD), pages 551-556, 2004.

Table 2. Comparisons between algorithms for cardinals numbers $k=2$ and $k=4$.

| Graph | balance $=1.00$ |  |  | balance $=1.01$ |  |  | balance $=1.03$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | JOSTLE | СНАСО | FF | JOSTLE | pM. | FF | JOSTLE | kM. | PARTY | FF |
| $k=2$ |  |  |  |  |  |  |  |  |  |  |
| add20 | 734 | 740 | 699 | 729 | 725 | 677 | 721 | 788 | 750 | 666 |
| data | 241 | 279 | 204 | 241 | 218 | 203 | 241 | 244 | 233 | 196 |
| 3 elt | 95 | 92 | 90 | 95 | 108 | 90 | 95 | 129 | 136 | 88 |
| uk | 33 | 34 | 21 | 28 | 23 | 21 | 25 | 41 | 29 | 19 |
| add32 | 12 | 28 | 11 | 10 | 21 | 10 | 10 | 50 | 23 | 10 |
| bcsstk33 | 12621 | 10224 | 10175 | 12616 | 10205 | 10175 | 12409 | 14655 | 12071 | 10069 |
| whitaker3 | 136 | 132 | 127 | 136 | 135 | 126 | 135 | 152 | 132 | 126 |
| crack | 207 | 209 | 186 | 196 | 187 | 186 | 199 | 278 | 222 | 186 |
| wingnodal | 1739 | 1828 | 1790 | 1741 | 1820 | 1748 | 1724 | 2054 | 1782 | 1735 |
| fe4elt2 | 130 | 130 | 130 | 130 | 130 | 130 | 130 | 143 | 130 | 130 |
| vibrobox | 11436 | 10346 | 11866 | 11424 | 12427 | 11552 | 11511 | 18245 | 11975 | 11440 |
| bcsstk29 | 2898 | 2917 | 2843 | 2898 | 2843 | 2818 | 2997 | 3904 | N/A | 2818 |
| 4 elt | 151 | 179 | 143 | 151 | 154 | 139 | 157 | 258 | 159 | 138 |
| fesphere | 466 | 422 | 386 | 466 | 440 | 386 | 468 | 568 | 386 | 384 |
| cti | 347 | 410 | 334 | 342 | 334 | 318 | 342 | 688 | 366 | 318 |
| memplus | 6141 | 6861 | 5816 | 6096 | 6337 | 5816 | 6047 | 6519 | 7604 | 5574 |
| cs4 | 455 | 421 | 414 | 435 | 414 | 414 | 406 | 613 | 418 | 414 |
| bcsstk30 | 6456 | 6447 | 6407 | 6599 | 6458 | 6345 | 6599 | 8297 | 6696 | 6275 |
| bcsstk31 | 4044 | 4020 | 2805 | 4060 | 3638 | 2718 | 4191 | 4950 | N/A | 2698 |
| bcsstk32 | 6764 | 5507 | 4782 | 7027 | 5672 | 4747 | 6888 | 5527 | 5520 | 4747 |
| t60k | 108 | 101 | 100 | 107 | 100 | 83 | 98 | 103 | 93 | 78 |
| wing | 956 | 952 | 950 | 908 | 950 | 908 | 896 | 1562 | 927 | 908 |
| brack2 | 754 | 752 | 738 | 751 | 738 | 714 | 715 | 845 | 947 | 691 |
| Best | 2 | 2 | 21 | 5 | 2 | 21 | 5 | 0 | 1 | 20 |
| $k=4$ |  |  |  |  |  |  |  |  |  |  |
| add20 | 1238 | 1357 | 1292 | 1229 | 1292 | 1211 | 1255 | 1387 | 1281 | 1202 |
| data | 448 | 433 | 459 | 447 | 480 | 430 | 425 | 505 | 511 | 420 |
| 3 elt | 212 | 219 | 212 | 210 | 231 | 210 | 201 | 265 | 243 | 208 |
| uk | 69 | 63 | 61 | 67 | 67 | 55 | 67 | 85 | 62 | 51 |
| add32 | 45 | 79 | 36 | 40 | 42 | 33 | 41 | 107 | 62 | 33 |
| bcsstk33 | 22130 | 26191 | 23066 | 22293 | 23131 | 22652 | 21590 | 25493 | 22445 | 21853 |
| whitaker3 | 417 | 398 | 406 | 403 | 406 | 397 | 406 | 575 | 399 | 396 |
| crack | 442 | 479 | 382 | 431 | 382 | 378 | 413 | 589 | 476 | 371 |
| wingnodal | 4073 | 3992 | 3720 | 4048 | 4000 | 3659 | 4048 | 4832 | N/A | 3659 |
| fe4elt2 | 396 | 356 | 359 | 375 | 359 | 351 | 368 | 1780 | 437 | 351 |
| vibrobox | 21761 | 21087 | 20282 | 22156 | 21471 | 19940 | 21844 | 36206 | N/A | 19825 |
| bcsstk29 | 9833 | 8831 | 8826 | 9122 | 8826 | 8692 | 9122 | 10851 | N/A | 8523 |
| 4 elt | 498 | 405 | 378 | 485 | 406 | 351 | 434 | 425 | 364 | 342 |
| fesphere | 825 | 868 | 844 | 818 | 872 | 825 | 806 | 1103 | 819 | 818 |
| cti | 1355 | 1016 | 1049 | 1357 | 1113 | 1029 | 1329 | 2294 | 1089 | 976 |
| memplus | 10696 | 11532 | 10596 | 10550 | 10559 | 10436 | 10470 | 10640 | 11406 | 10182 |
| cs4 | 1194 | 1132 | 1154 | 1177 | 1154 | 1102 | 1162 | 1599 | N/A | 1089 |
| bcsstk30 | 25825 | 17013 | 17443 | 25865 | 17685 | 16816 | 25438 | 24151 | N/A | 16767 |
| bcsstk31 | 10190 | 10184 | 8201 | 10066 | 8770 | 7812 | 10134 | 15279 | N/A | 7812 |
| bcsstk32 | 14890 | 14946 | 12205 | 14887 | 12205 | 11340 | 14887 | 16215 | 13333 | 9924 |
| t60k | 240 | 290 | 255 | 229 | 255 | 255 | 242 | 279 | 272 | 227 |
| wing | 1922 | 2161 | 1937 | 1840 | 2086 | 1937 | 1824 | 3454 | N/A | 1900 |
| brack2 | 3222 | 3356 | 3705 | 3144 | 3250 | 3109 | 2999 | 4129 | N/A | 2935 |
| Best | 6 | 6 | 12 | 5 | 0 | 19 | 4 | 0 | 0 | 19 |

Table 3. Comparisons between algorithms for cardinals numbers $k=8$ and $k=16$.

| Graph | $\begin{array}{r} \text { balar } \\ \text { JOSTLE } \end{array}$ | $\begin{array}{ll}\text { cee }=1.00 & \\ \text { CHACO } & \text { FF }\end{array}$ | $\begin{array}{r} \text { balar } \\ \text { JOSTLE } \end{array}$ | $\begin{array}{ll} \hline c e=1.01 & \\ \text { METIS } & \text { FF } \\ \hline \end{array}$ | JOSTLE | balance $=$ | $\begin{aligned} & 1.03 \\ & \text { eARTY } \end{aligned}$ | FF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $k=8$ |  |  |  |  |  |  |  |  |
| add20 | 1853 | 1881 1907 | 1894 | 19071907 | 1836 | 2130 | 2018 | 1907 |
| data | 798 | 763842 | 800 | 842758 | 756 | N/A | 791 | 714 |
| 3elt | 462 | $393 \mathbf{3 8 8}$ | 433 | $388 \mathbf{3 6 4}$ | 418 | 527 | 432 | 356 |
| uk | 114 | 130101 | 104 | 101101 | 106 | 168 | 148 | 101 |
| add32 | 120 | 139 N/A | 105 | $81 \quad 81$ | 106 | 351 | N/A | 72 |
| bcsstk33 | 36106 | 4195140070 | 36269 | 4007035579 | 35961 | 44681 | 39071 | 34919 |
| whitaker3 | 716 | 712719 | 710 | $719 \mathbf{6 9 2}$ | 706 | 1047 | 759 | 687 |
| crack | 809 | $806 \quad \mathbf{7 7 3}$ | 779 | $773 \mathbf{7 2 1}$ | 751 | 1047 | 808 | 721 |
| wingnodal | 6070 | $6152 \mathbf{6 0 7 0}$ | 6033 | 60706070 | 5965 | 8335 | 6284 | 5976 |
| fe4elt2 | 713 | 651654 | 688 | 654646 | 681 | 801 | 707 | 641 |
| vibrobox | 30103 | 3341028696 | 31032 | 2817726162 | 30247 | 43334 | N/A | 25796 |
| bcsstk29 | 17391 | 1688717534 | 16742 | 1655515181 | 17234 | 24525 | N/A | 15043 |
| 4 elt | 674 | 701635 | 612 | $635 \quad 604$ | 656 | 827 | 722 | 583 |
| fesphere | 1351 | 13371330 | 1280 | 13301302 | 1274 | 1643 | 1277 | 1294 |
| cti | 2257 | $1886 \mathrm{~N} / \mathrm{A}$ | 2158 | 21102076 | 2086 | 3888 | 2482 | 2005 |
| memplus | 12866 | 1395613110 | 12684 | 1311013110 | 12540 | N/A | 13119 | 13110 |
| cs4 | 1703 | 18081746 | 1673 | 17461746 | 1588 | 2733 | 1721 | 1746 |
| bcsstk30 | 39271 | 35647 N/A | 38746 | 3635736357 | 38228 | 41052 | 48539 | 35668 |
| bcsstk31 | 15360 | 1755316012 | 17094 | 1601214754 | 19849 | 20647 | N/A | 14754 |
| bcsstk32 | 29281 | 2581023601 | 26655 | 2360123601 | 25343 | 39817 | N/A | 23601 |
| t60k | 556 | 593561 | 532 | 561561 | 530 | 1309 | 581 | 561 |
| wing | 3028 | 32213205 | 2918 | 32053205 | 2911 | 5748 | N/A | 3205 |
| brack2 | 8007 | $8061 \quad \mathbf{7 8 4 4}$ | 8037 | $\mathbf{7 8 4 4} \mathbf{7 8 4 4}$ | 7757 | 10171 | N/A | 7844 |
| Best | 9 | $6 \quad 9$ | 7 | $5 \quad 16$ | 8 | 0 | 0 | 15 |
| $k=16$ |  |  |  |  |  |  |  |  |
| add20 | 2555 | $2269 \quad \mathbf{2 5 0 4}$ | 2532 | $2504 \quad 2504$ | 2565 | N/A | 2510 | 2504 |
| data | 1299 | 12791309 | 1299 | 13701278 | 1263 | 4857 | 1475 | 1224 |
| 3elt | 645 | 641665 | 621 | $665 \quad 607$ | 603 | 969 | 754 | 598 |
| uk | 211 | 211 N/A | 190 | 189189 | 180 | 384 | 220 | 189 |
| add32 | 269 | $217 \quad 128$ | 239 | 128128 | 180 | N/A | N/A | 128 |
| bcsstk33 | 59884 | 6180059791 | 61505 | 5979158694 | 57553 | 123044 | 61630 | 58183 |
| whitaker3 | 1172 | $1241 \quad 1237$ | 1138 | 12371180 | 1147 | 1436 | 1277 | 1165 |
| crack | 1245 | 12771255 | 1212 | 125511197 | 1191 | 2296 | 1263 | 1187 |
| wingnodal | 9083 | $9327 \quad 9290$ | 9091 | 929088962 | 8947 | 10097 | 9006 | 8890 |
| fe4elt2 | 1194 | 10951152 | 1146 | 11521083 | 1140 | 1500 | 1236 | 1076 |
| vibrobox | 35447 | 4263437441 | 36233 | 3744136398 | 34521 | N/A | N/A | 35809 |
| bcsstk29 | 28294 | 26239 N/A | 28062 | 2815126422 | 28338 | 147143 | N/A | 25417 |
| 4 elt | 1081 | 10991056 | 1034 | 10561048 | 1012 | 5077 | 1282 | 1015 |
| fesphere | 1918 | 20612030 | 1759 | 20301952 | 1741 | 2495 | N/A | 1943 |
| cti | 3402 | 31223181 | 3345 | 31813181 | 3262 | 4760 | N/A | 3181 |
| memplus | 14510 | 15654 N/A | 15085 | 1494214942 | 13958 | 15804 | 14831 | 14942 |
| cs4 | 2518 | 25502538 | 2519 | $2538 \quad 2538$ | 2477 | 3614 | 2488 | 2538 |
| bcsstk30 | 87824 | 79046 N/A | 87472 | 7729377293 | 81764 | 93834 | N/A | 76791 |
| bcsstk31 | 27897 | 2936427180 | 27954 | 2718027180 | 27388 | 189562 | N/A | 27180 |
| bcsstk32 | 46954 | 4626643371 | 48162 | 4337143371 | 48395 | 50660 | N/A | 43371 |
| t60k | 977 | 1027 N/A | 969 | 998998 | 984 | 1347 | 1097 | 998 |
| wing | 4761 | $4806 \mathbf{4 6 6 6}$ | 4623 | 46664666 | 4681 | 7712 | N/A | 4666 |
| brack2 | 13318 | 1311712655 | 13337 | 1265512655 | 13164 | 150514 | N/A | 12655 |
| Best | 9 | 78 | 7 | $9 \quad 16$ | 9 | 0 | 0 | 14 |

[DGK07] Inderjit S. Dhillon, Yuqiang Guan, and Brian Kulis. Weighted graph cuts without eigenvectors: A multilevel approach. IEEE Transactions on Pattern Analysis and Machine Intelligence, 2007. To appear.
[DMP95] R. Diekmann, B. Monien, and R. Preis. Using helpful sets to improve graph bisections. In Proceedings of the DIMACS Workshop on Interconnection Networks and Mapping and Scheduling Parallel Computations, pages 5773, 1995.
[FM82] C. M. Fiduccia and R. M. Mattheyses. A linear-time heuristic for improving network partitions. In Proceedings of 19th ACM/IEEE Design Automation Conference, pages 175-181, 1982.
[HL95a] Bruce Hendrickson and Robert Leland. The Chaco User's Guide. Sandia National Laboratories, 2.0 edition, 1995.
[HL95b] Bruce Hendrickson and Robert W. Leland. A multilevel algorithm for partitioning graphs. In Proceedings of Supercomputing, 1995.
[KcR04] Peter Korošec, Jurij Šilc, and Borut Robič. Solving the mesh-partitioning problem with an ant-colony algorithm. Parallel Computing, 30(5-6):785801, 2004.
[KK95] George Karypis and Vipin Kumar. Analysis of multilevel graph partitioning. In Proceedings of Supercomputing, 1995.
[KK98a] George Karypis and Vipin Kumar. A fast and high quality multilevel scheme for partitioning irregular graphs. SIAM Journal of Scientific Computing, 20(1):359-392, 1998.
[KK98b] George Karypis and Vipin Kumar. Metis : A Software Package for Partitioning Unstructured Graphs, Partitioning Meshes, and Computing FillReducing Orderings of Sparse Matrices. University of Minnesota, 4.0 edition, sep 1998.
[KK98c] George Karypis and Vipin Kumar. Multilevel k-way partitioning scheme for irregular graphs. Journal of Parallel and Distributed Computing, 48(1):96129, 1998.
[KL70] B. W. Kernighan and S. Lin. An efficient heuristic procedure for partitioning graphs. Bell System Technical Journal, 49(2):291-307, 1970.
[PD98] Robert Preis and Ralf Diekmann. The Party Partitioning Library, User Guide. University of Paderborn, 1.99 edition, oct 1998.
[SM00] Jianbo Shi and Jitendra Malik. Normalized cuts and image segmentation. IEEE Transactions on Pattern Analysis and Machine Intelligence, 22(8):888-905, 2000.
[ST97] Horst D. Simon and Shang-Hua Teng. How good is recursive bisection? SIAM Journal on Scientific Computing, 18(5):1436-1445, 1997.
[SWC04] Alan J. Soper, Chris Walshaw, and M. Cross. A combined evolutionary search and multilevel optimisation approach to graph-partitioning. Journal of Global Optimization, 29:225-241, 2004.
[Wal02] Chris Walshaw. The serial JOSTLE library user guide. University of Greenwich, 3.0 edition, jul 2002.
[WC00] Chris Walshaw and M. Cross. Mesh partitioning: A multilevel balancing and refinement algorithm. SIAM Journal on Scientific Computing, 22:6380, 2000.

